

Analytics Setup for Trojan Cameras

This document will give step-by-step instructions on how to set-up the following features on using the Hikvision video interface:

- Line crossing detection.
- Privacy masking.
- Unattended Baggage Detection.
- Object Removal Detection

You will need:

If you are accessing the unit via Wi-Fi:

- o Computer/Laptop with Wi-Fi access.
- o Wi-Fi password.
- o Username and Password of the Camera on the unit.
- o Internal IP address of the unit.

If you are accessing the unit via SIM card:

- o Computer/Laptop with Internet access.
- o IP Address of SIM card.
- o Username and Password of the Camera on the unit.

An internet Browser of your choosing (we recommend using Internet Explorer).

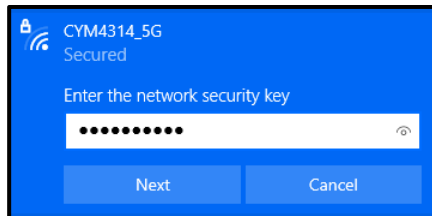
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1) Connecting to the Camera.

a) Connecting via Wi-Fi.

- i) Use a device which has Wi-Fi access, select the unit you wish to connect to and enter the Wi-Fi password.

(1) Revader Default password: **aaiffbbfcc**

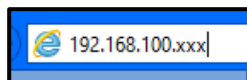


b) Logging into Camera/NVR.

- i) Open the browser of your choosing (we recommend Internet Explorer).
- ii) Go to the IP address of the Camera/NVR.

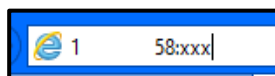
(1) Revader default Internal Camera IP: **192.168.100.223**

(2) Revader default Internal NVR IP: **192.168.100.222**



(3) Or if accessing the Camera head via SIM card, enter the External IP address followed by: **:223**

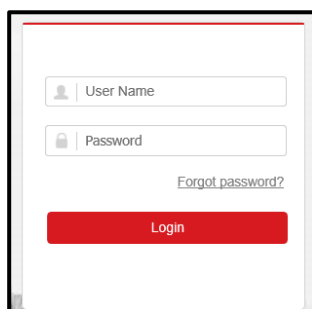
(4) If accessing the NVR via SIM card, enter the external IP address followed by: **:222**



- iii) Enter the **User Name** and **Password** of the Camera/NVR.

(1) Revader Default Username: **admin**

(2) Revader Default Password: **Compress1766**



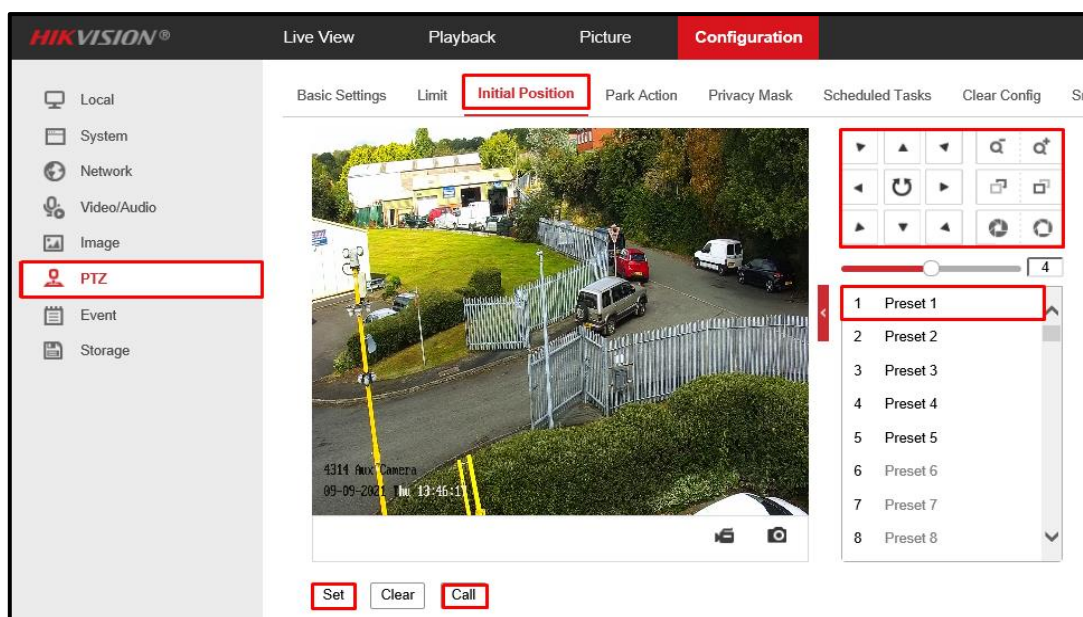
2) Line Crossing Detection.

a) Setting Initial Position.

- i) This is so when the Camera has finished tracking the target, it will go back to the initial position set.
- ii) Go to the Camera (**Follow section 1**).
- iii) Go to **Configuration**.

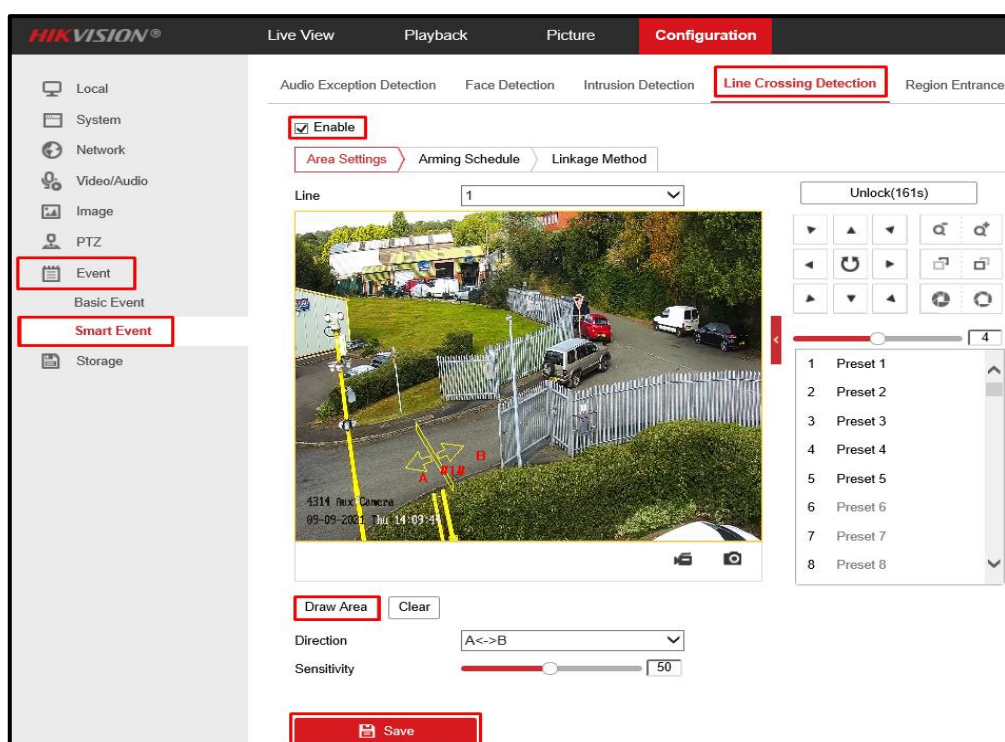


- iv) Go to **PTZ - Initial Position**, move the Camera to the position in which it will default back to after tracking an object using the PTZ controls on the right of the screen. Select **Preset 1** and **Set**. This will store your initial position.
- v) To check that it is set to your required position, move the camera using the PTZ controls to a different position and select **Call** - the camera should move back to the stored initial position.

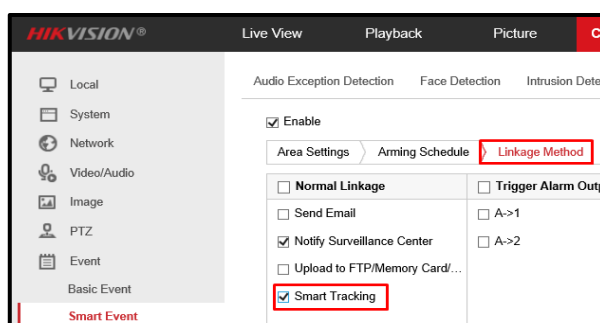


b) Setting up Line Crossing Detection

- i) Go to **Event - Smart Event - Line Crossing Detection**.
- ii) Click **Enable - Draw Area** and this will insert a line on the image, move the line to where you wish.
- iii) There are custom options below such as **Direction**, which is the direction of which the line is triggered. **Sensitivity** can be increased or decreased depending on the environment in which the Trojan is located. Generally, the smaller and slower the object the higher the sensitivity is needed.
- iv) Click **Save**.

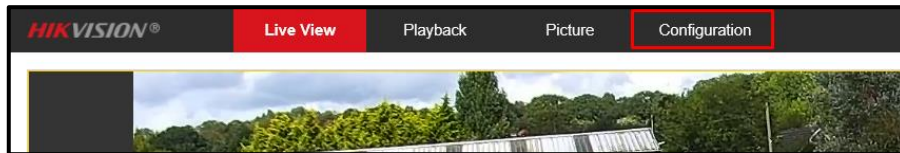


- v) Click **Linkage Method** and ensure **Smart Tracking** is selected. This will allow the camera to follow an object which triggers the line.
- vi) Click **Save**.

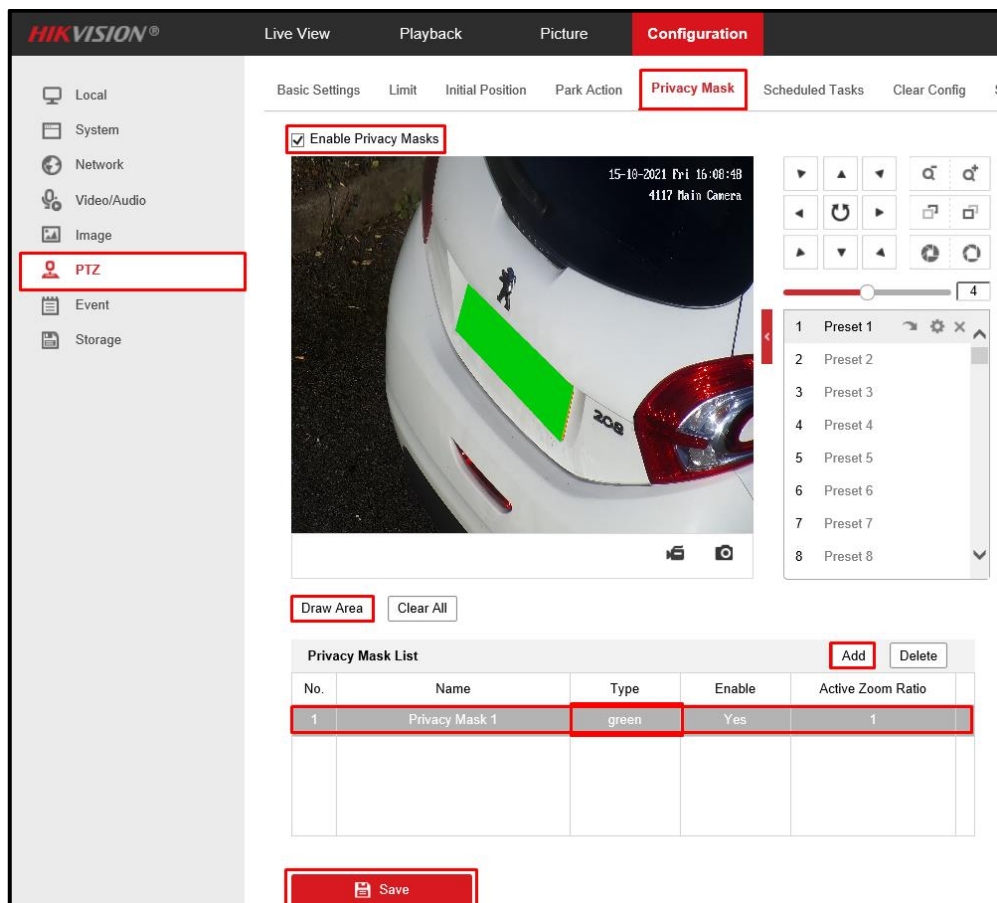


3) Privacy Masking.

- a) Setting up Privacy Masking.
 - i) Go to the Camera (**follow section 1**).
 - ii) Go to **Configuration**.

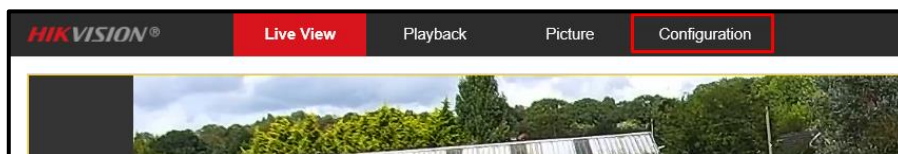


- iii) Go to **PTZ – Privacy Mask**.
- iv) Click **Enable Privacy Masks**.
- v) Click **Draw Area**, click the 4 corners where you wish the privacy mask to be, in the example below, the 4 corners of the license plate were clicked.
- vi) Once satisfied click **Stop Drawing – Add**, you will now see the mask listed below, here you can change the colour of the masks as well as delete it.
- vii) Click **Save**
- viii) If you wish to add more repeat steps **iv, v** and **vi** above.

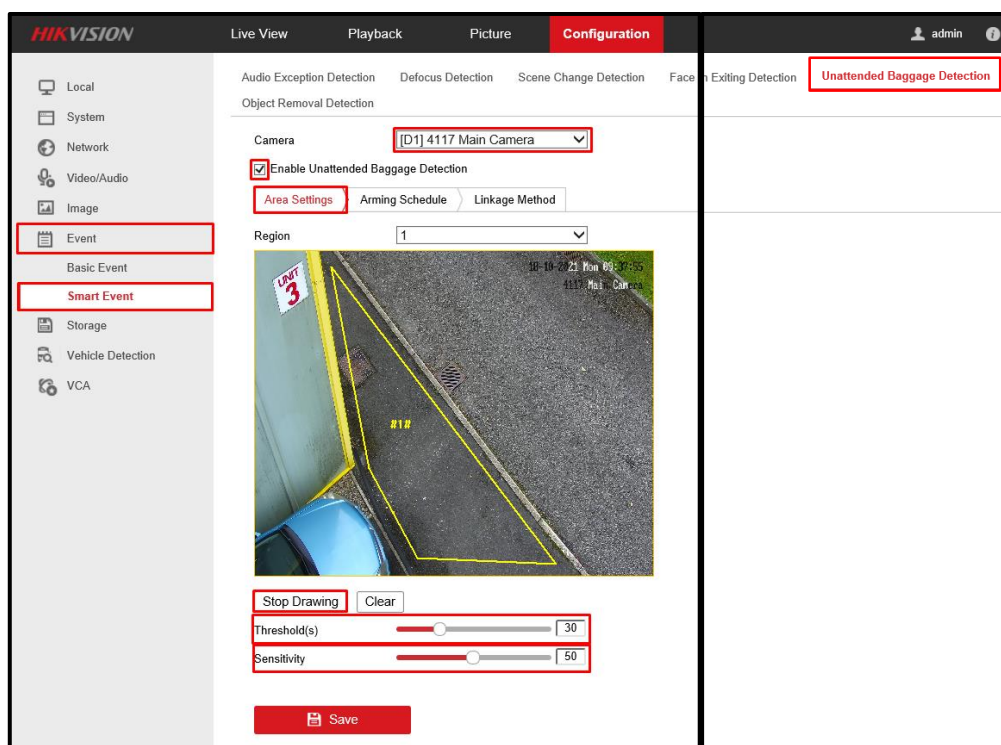


4) Unattended Baggage Detection

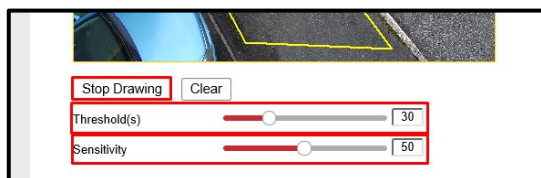
- a) Setting up Unattended Baggage Detection.
 - i) Go to the NVR (**follow section 1**).
 - ii) There are no PTZ controls in the Unattended Baggage detection menu, so the PTZ will have to be moved to the position before moving on.
 - iii) Go to **Configuration**.



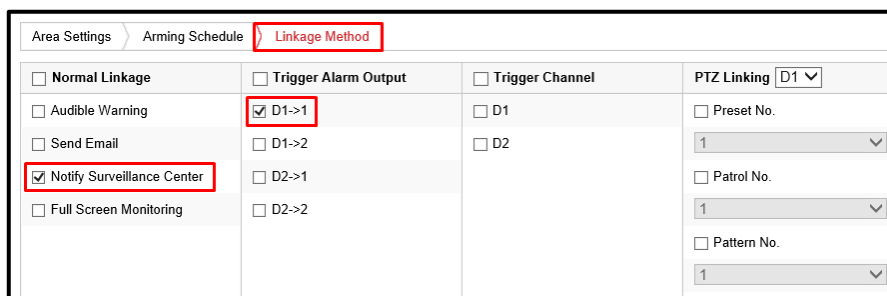
- iv) Go to **Event – Smart Event – Unattended Baggage Detection**.
- v) Select the camera you wish to apply this to.
- vi) Click **Enable Unattended Baggage Detection**.
- vii) Click **Draw Area**, click the 4 corners where you wish to monitor. In the example below, the 4 corners of the pathway.
- viii) Once satisfied, click **Stop Drawing**. You can click clear, which will delete all selected areas.
- ix) You can select a different **Region**, this will allow you to set up to 4 different areas.



- x) **Threshold** is the number of seconds the object can stay there before being picked up by the NVR.
- xi) **Sensitivity** is how sensitive the detection is. The higher the number the smaller the object.
- xii) Click **Save**

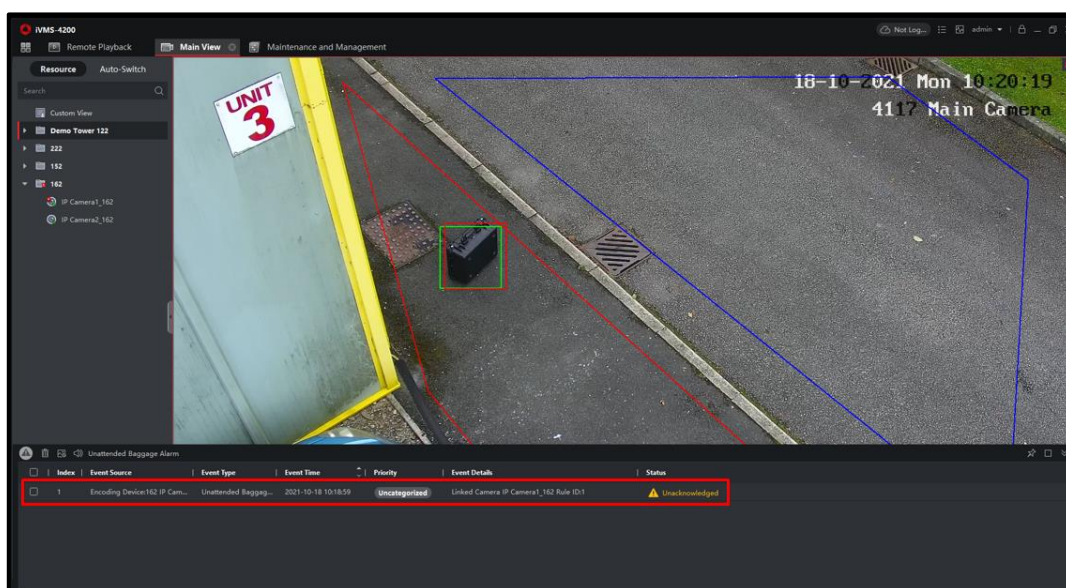


- xiii) Go to **Linkage Method** and Click **Notify Surveillance Centre**, the NVR will now send an alert to the IVMS software when baggage is detected.
- xiv) If you have a Revader Speaker/Amplifier, you can enable **D1->1** and this will trigger the speaker and send out an alarm when baggage is detected.
- xv) There are other settings you can configure if you wish.



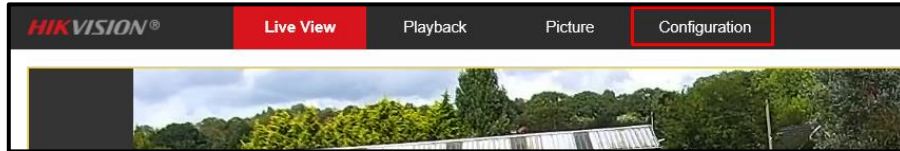
b) Unattended Baggage Detection example.

- i) In the IVMS software, in **Main View** Alarm is shown at the bottom of the image, just press the 2 arrows in the bottom right to pop up the menu.

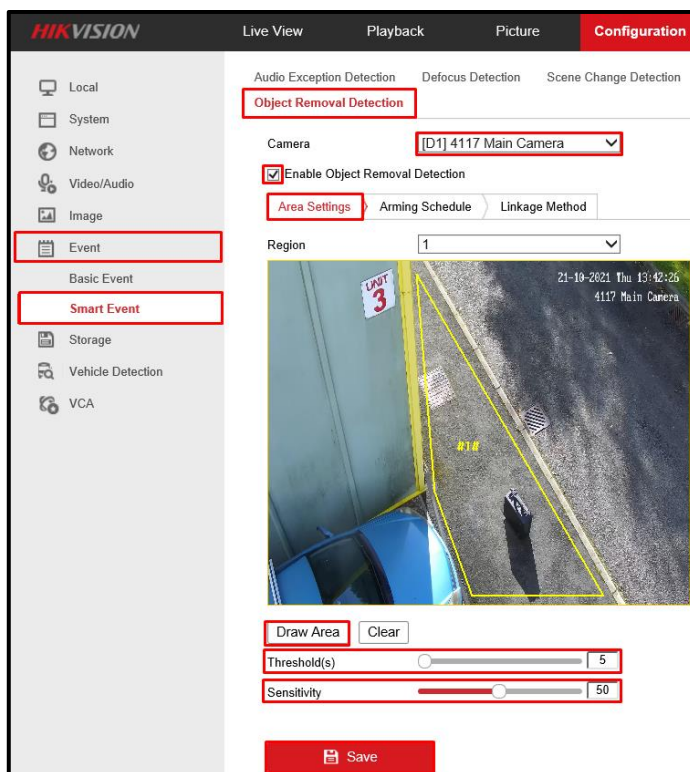


5) Object Removal Detection

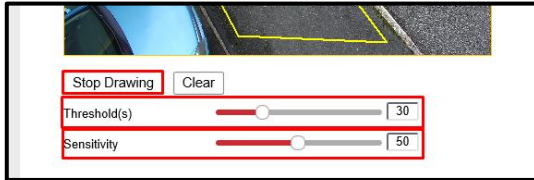
- a) Setting up Object Removal Detection.
 - i) Go to the NVR (**follow section 1**).
 - ii) There are no PTZ controls in the Object Removal detection menu, so the PTZ will have to be moved to the position before moving on.
 - iii) Go to **Configuration**.



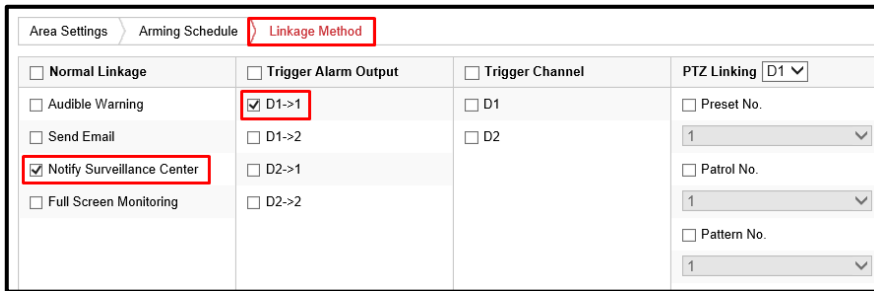
- iv) Go to **Event – Smart Event – Object Removal Detection**.
- v) Select the camera you wish to apply this to.
- vi) Click **Enable Object Removal Detection**.
- vii) Click **Draw Area**, click the 4 corners where you wish to monitor, in the example below, the 4 corners of the pathway.
- viii) Once satisfied click **Stop Drawing**, you can click clear, which will delete all selected areas.
- ix) You can select a different **Region**, this will allow you to set up to 4 different areas.



- x) **Threshold** is the number of seconds the object can be missing before being picked up by the NVR.
- xi) **Sensitivity** is how sensitive the detection is, the higher the number the smaller the object.
- xii) Click **Save**



- xiii) Go to **Linkage Method** and Click **Notify Surveillance Centre**, the NVR will now send an alert to the iVMS software when an object is missing.
- xiv) If you have a Revader Speaker/Amplifier, you can enable **D1->1** and this will trigger the speaker and send out an alarm when an object is missing.
- xv) There are other settings you can configure if you wish.



b) Object Removal Detection example.

- i) In the iVMS software, in **Main View**, Alarm is shown at the bottom of the image, just press the 2 arrows in the bottom right to pop up the menu.

